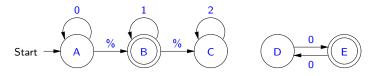
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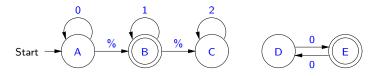
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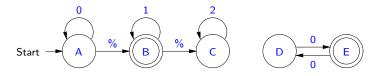


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First, there are no valid labeled paths from the start state to ${\sf D}$ and ${\sf E}$, and so these states are redundant.

Second, there are no valid labeled paths from C to an accepting state, and so it is also redundant.

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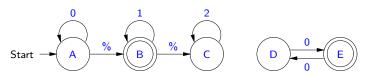
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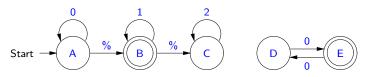
- reachable in M iff there is a labeled path Ip such that Ip is valid for M, the start state of Ip is s_M, and the end state of Ip is q;
- live in M iff there is a labeled path lp such that lp is valid for M, the start state of lp is q, and the end state of lp is in A_M;
- dead in M iff q is not live in M; and
- useful in M iff q is both reachable and live in M.

Let M be our example finite automaton:



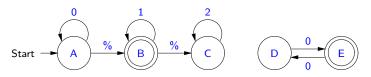
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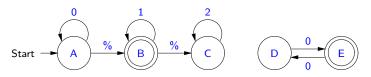
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There is a simple algorithm for generating the set of reachable states of a finite automaton M. We generate the least subset X of Q_M such that:

- $\in X$; and
- for all $q, r \in Q_M$ and $x \in Str$, if $\in X$ and $(q, x, r) \in T_M$, then $\in X$.

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Similarly, there is a simple algorithm for generating the set of live states of a finite automaton M. We generate the least subset Y of Q_M such that:

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Similarly, there is a simple algorithm for generating the set of live states of a finite automaton M. We generate the least subset Y of Q_M such that:

- $A_M \subset Y$; and
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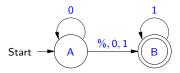
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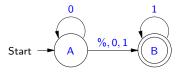
Thus, we can generate the set of useful states of an FA by generating the set of reachable states, generating the set of live states, and intersecting those sets of states.

Now, suppose N is the FA



What is odd about this machine?

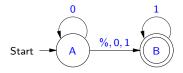
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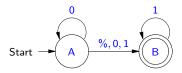


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Given an FA M and a finite subset U of $\{(q, x, r) \mid q, r \in Q_M \text{ and } x \in \mathbf{Str}\}$, we write M/U for the FA that is identical to M except that its set of transitions is U.

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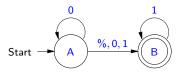
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If M is an FA and $(p, x, q) \in T_M$, we say that:

• (p, x, q) is redundant in M iff $q \in \Delta_N(\{p\}, x)$, where $N = M/(T_M - \{(p, x, q)\})$; and

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- (p, x, q) is redundant in M iff $q \in \Delta_N(\{p\}, x)$, where $N = M/(T_M \{(p, x, q)\})$; and
- (p, x, q) is irredundant in M iff (p, x, q) is not redundant in M.



We say that a finite automaton M is *simplified* iff either

 every state of M is useful, and every transition of M is irredundant; or

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Proposition 3.7.1

If M is a simplified finite automaton, then alphabet(L(M)) = alphabet M.

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Given an FA M, we define a function $\mathbf{remRedun}_M \in \mathcal{P} \ T_M \times \mathcal{P} \ T_M \to \mathcal{P} \ T_M$ by well-founded recursion on the size of its second argument.

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For $U, V \subseteq T_M$, remRedun(U, V) proceeds as follows:

• If $V = \emptyset$, then it returns U.

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Given an FA M, we define a function $\mathbf{remRedun}_M \in \mathcal{P} T_M \times \mathcal{P} T_M \to \mathcal{P} T_M$ by well-founded recursion on the size of its second argument.

- If $V = \emptyset$, then it returns U.
- Otherwise, let v be the greatest element of $\{(q, x, r) \in V \mid \text{there are no } q', r' \in \mathbf{Sym} \text{ and } y \in \mathbf{Str} \text{ such that } (q', y, r') \in V \text{ and } |y| > |x| \}, \text{ and } V' = V \{v\}.$

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In general, there are multiple—incompatible—ways of removing redundant transitions from an FA. **remRedun** is defined so as to favor removing transitions whose labels are longer; and among transitions whose labels have equal length, to favor removing transitions that are larger in our total ordering on transitions.

Simplification Algorithm

We define a function **simplify** \in **FA** \to **FA** by: **simplify** M is the finite automaton N produced by the following process.

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 - $T_N = \emptyset$.
- And, if s_M is useful in M, then N is $\operatorname{remRedun}_{N'}(\emptyset, T_{N'})$, where N' is defined by
 - $Q_{N'} = \{ q \in Q_M \mid q \text{ is useful in } M \};$
 - $s_{N'}=s_M$;
 - $A_{N'} = A_M \cap Q_{N'} = \{ q \in A_M \mid q \in Q_{N'} \}$; and
 - $T_{N'} = \{ (q, x, r) \in T_M \mid q, r \in Q_{N'} \}.$

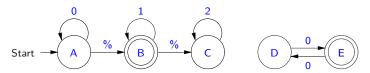
More on Simplification Algorithm

Proposition 3.7.3

Suppose M is a finite automaton. Then:

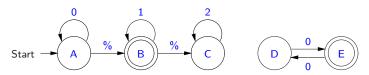
- (1) simplify M is simplified;
- (2) simplify $M \approx M$;
- (3) $Q_{\text{simplify }M} \subseteq Q_M$ and $T_{\text{simplify }M} \subseteq T_M$; and
- (4) $alphabet(simplify M) = alphabet(L(M)) \subseteq alphabet M$.

If *M* is the finite automaton

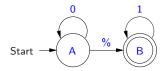


then simplify M is the finite automaton

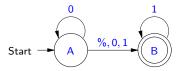
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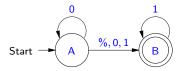


If N is the finite automaton

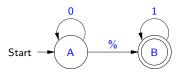


then **simplify** *N* is the finite automaton

If N is the finite automaton



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Testing Whether $L(M) = \emptyset$

Our simplification algorithm gives us an algorithm for testing whether the language accepted by an FA M is empty. We first simplify M, calling the result N. We then test whether

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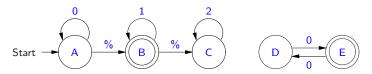
Our simplification algorithm gives us an algorithm for testing whether the language accepted by an FA M is empty. We first simplify M, calling the result N. We then test whether $A_N=\emptyset$. If the answer is "yes", clearly $L(M)=L(N)=\emptyset$. And if the answer is "no", then s_N is useful, and so N (and thus M) accepts at least one string.

Simplification in Forlan

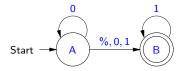
The Forlan module FA includes the following functions relating to the simplification of finite automata:

```
val simplify : fa -> fa
val simplified : fa -> bool
```

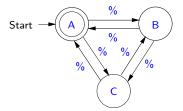
In the following, suppose fal is the finite automaton



fa2 is the finite automaton



and fa3 is the finita automaton



Here are some example uses of simplify and simplified:

```
- FA.simplified fa1;
val it = false : bool
- val fa1' = FA.simplify fa1;
val fa1' = - : fa
- FA.output("", fa1');
{states} A, B {start state} A {accepting states} B
\{transitions\}\ A, \% \rightarrow B; A, O \rightarrow A; B, 1 \rightarrow B
val it = () : unit
- FA.simplified fa1';
val it = true : bool
- val fa2' = FA.simplify fa2;
val fa2' = - : fa
- FA.output("", fa2');
{states} A, B {start state} A {accepting states} B
\{transitions\}\ A, \% \rightarrow B; A, O \rightarrow A; B, 1 \rightarrow B
val it = () : unit
```

```
- val fa3' = FA.simplify fa3;
val fa3' = - : fa
- FA.output("", fa3');
{states} A, B, C {start state} A {accepting states} A
{transitions} A, % -> B | C; B, % -> A; C, % -> A
val it = () : unit
```

Thus the simplification of fa3 resulted in the removal of the %-transitions between B and C.